Supplementary Material

Application of tri-axial accelerometer data to the interpretation of movement and behaviour of threatened black cockatoos

Lian Yeap^{A,D}, Kristin S. Warren^A, Willem Bouten^C, Rebecca Vaughan-Higgins^A, Bethany Jackson^A, Karen Riley^B, Sam Rycken^B and Jill M. Shephard^A

^AHarry Butler Institute, Murdoch University, 90 South Street, Murdoch, WA 6150, Australia.

^BConservation Medicine Program, School of Veterinary Medicine, College of Science, Health, Engineering and Education, Murdoch University, 90 South Street, Murdoch, WA 6150, Australia.

^CInstitute for Biodiversity and Ecosystem Dynamics, University of Amsterdam, Sciencepark 904, 1098 XH, Amsterdam, The Netherlands.

^DCorresponding author. Email: L.Yeap@murdoch.edu.au

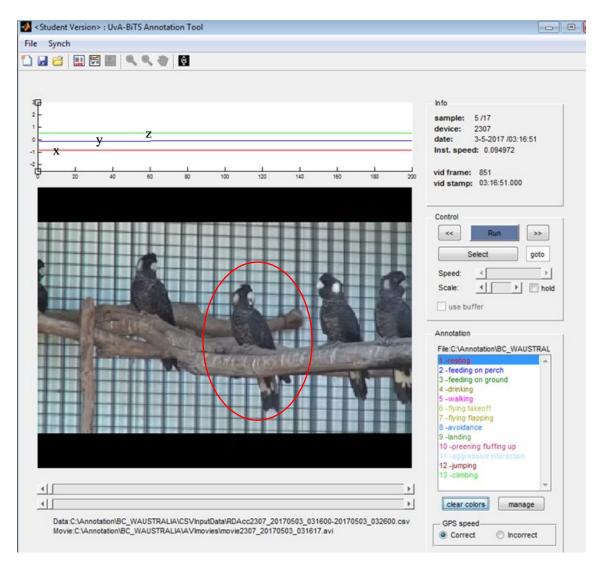


Figure S1. Typical flat accelerometer signature for resting behaviour with accompanying video footage of black cockatoo at rest (study bird circled in red). 200 accelerometer measurements per video frame. x – surge, red line; y – sway, blue line; z – heave, green line.

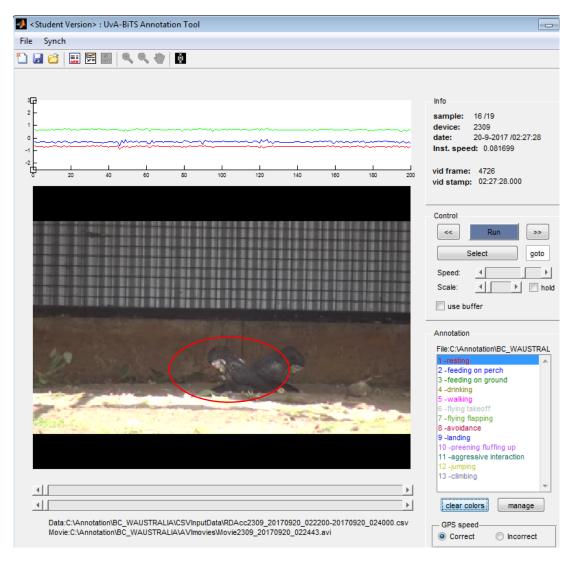


Figure S2. Typical accelerometer signature for feeding/foraging behaviour with accompanying video footage of black cockatoo feeding on the ground (study bird circled in red). 200 accelerometer measurements per video frame. x - surge, red line; y - sway, blue line; z - heave, green line.

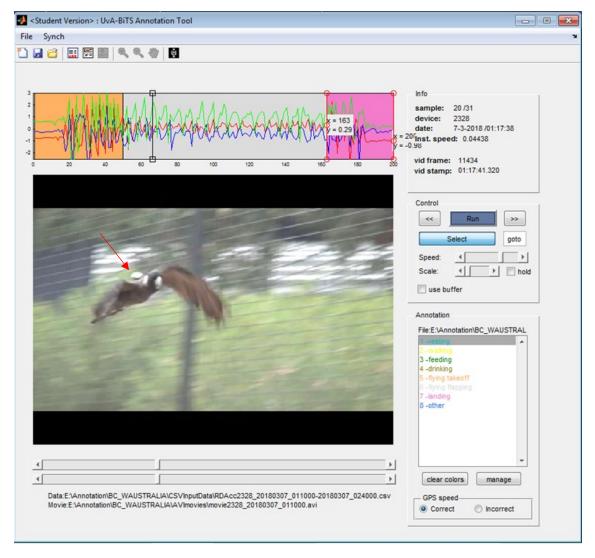


Figure S3. Typical accelerometer signature for flying behaviour with accompanying video footage of black cockatoo in flight. 200 accelerometer measurements per video frame. Red arrow indicates the UvA-BiTs tag attached to the back of the bird. x – surge, red line; y – sway, blue line; z – heave, green line.

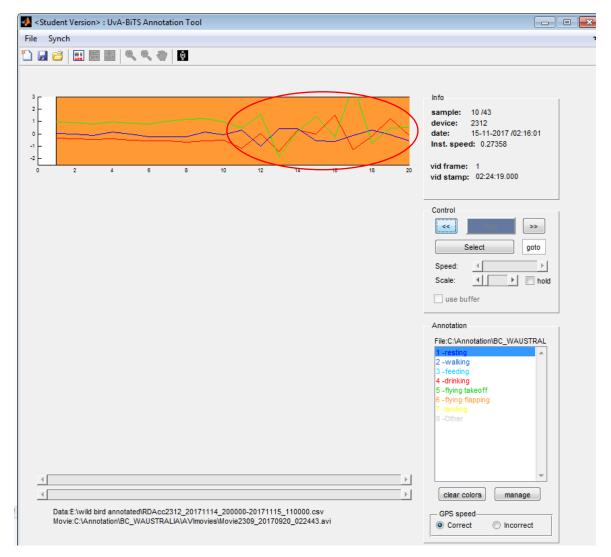


Figure S4. Typical accelerometer signature for flying behaviour (circled in red) without accompanying video footage. 20 accelerometer measurements per frame. x - surge, red line; y - sway, blue line; z - heave, green line.